

Final Data for the ELTE-Bosch Parking Car Competition

The final data are going to be published on **2nd May, 9:00AM** in the website. The detection results must be submitted until **17:00PM** to haider@inf.elte.hu .

There will be *six individual testing scenes* to evaluate the detectors.

The data will be given in one ZIP file. There will be six folders called Scene13, Scene14, ..., Scene18. Each folder will contain a short sequence with images files and LiDAR scans. The lengths of the sequences are not fixed, each folder contains 20-50 scans/recordings.

The file names are the same as those of published testing data. LiDAR scans are contained by file test_fn*.xyz where * denotes the frame number. Image files are named as DevN_Image_w960_h600_fn*.jpg. Here, $N=\{0,1,2\}$ is the camera index.

Results

The results should be given by only six files. You can add the result by 3D coordinates in the last LiDAR cloud or in one of the last camera images. The file format must be the same as in the [annotated data](#). The file name must be 'SceneXX_devM.txt', where $XX=\{13,14,15,16,18\}$ is the scene number, $M=\{0,1,2,3\}$ the device identifier. $M=3$ is the LiDAR, if M is 0, 1, or 2, then it encodes the camera (device) index.

Remark that the implementation should be fully automatic. Students must present their implementation in operation if they get good scores.